



Group Equivariant Deep Learning

Lecture 2 - Steerable group convolutions

Lecture 2.3 - Group Theory | Irreducible representations and Fourier trafo

Preliminaries for steerable feature fields and steerable g-conv intuition

With a focus on $SO(2)$

Equivalence of group representations

Two representations $\rho^A(g)$ and $\rho^B(g)$ are said to be **equivalent** if they relate via a similarity transform

$$\rho^B(g) = Q^{-1} \rho^A(g) Q$$

in which Q carries out the change of basis.

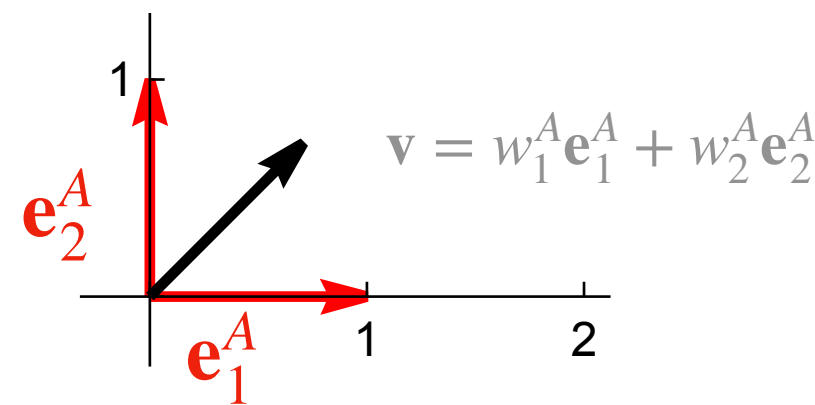
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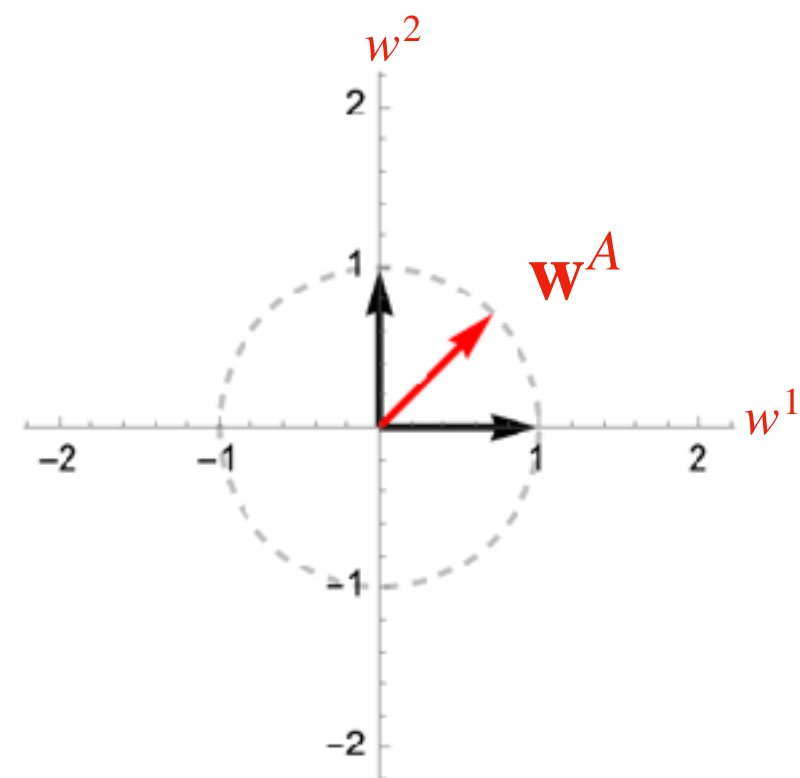
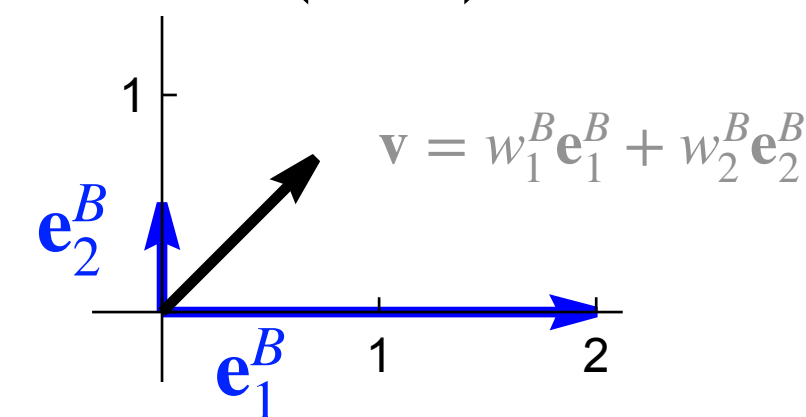
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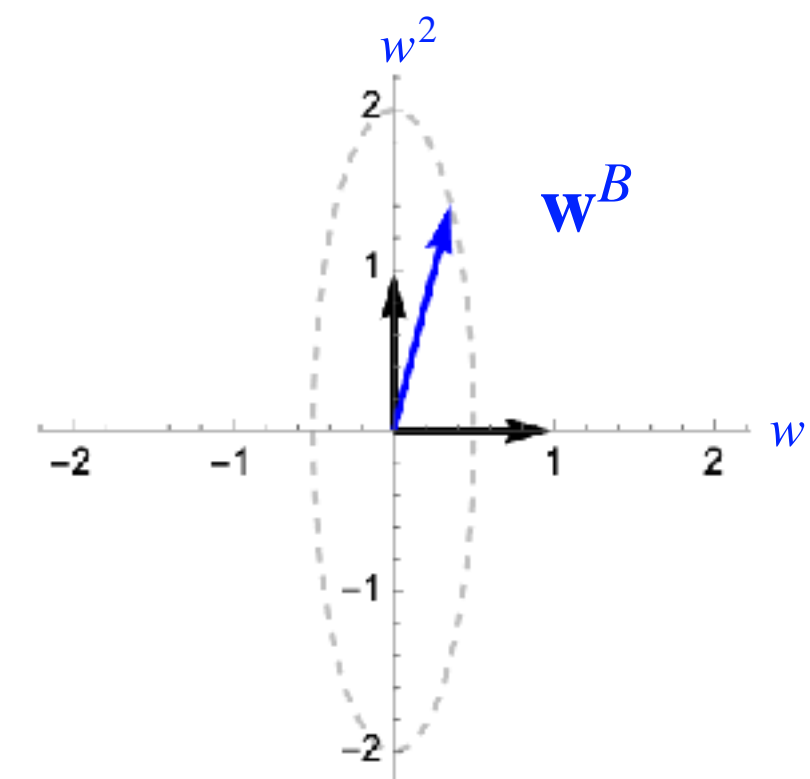
Standard basis for \mathbb{R}^2



Scaled basis $Q = \begin{pmatrix} 2 & 0 \\ 0 & \frac{1}{2} \end{pmatrix} = (e_1^B, e_2^B)$



$$\begin{aligned} \overrightarrow{w^A} &= Q \overrightarrow{w^B} \\ \overleftarrow{w^B} &= Q^{-1} \overleftarrow{w^A} \end{aligned}$$



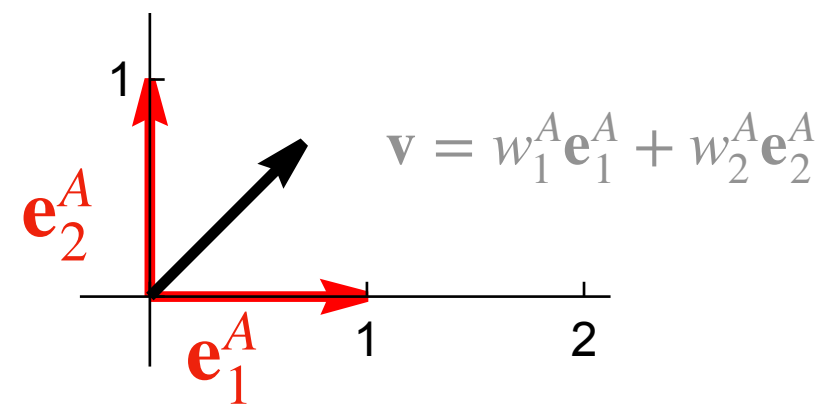
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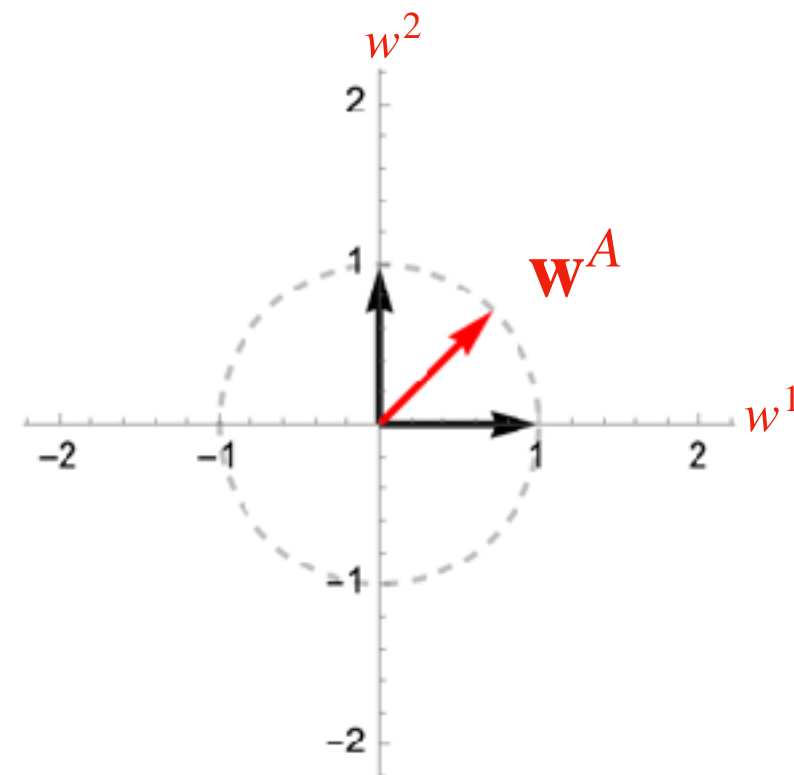
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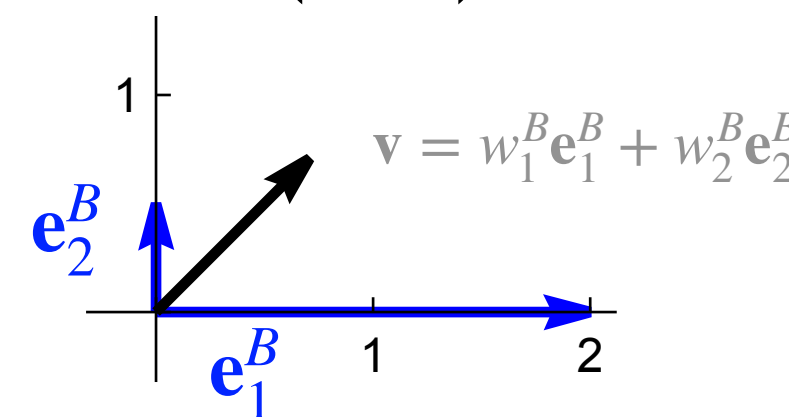


Transforms via $\rho^A(\mathbf{R}_\theta) = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$

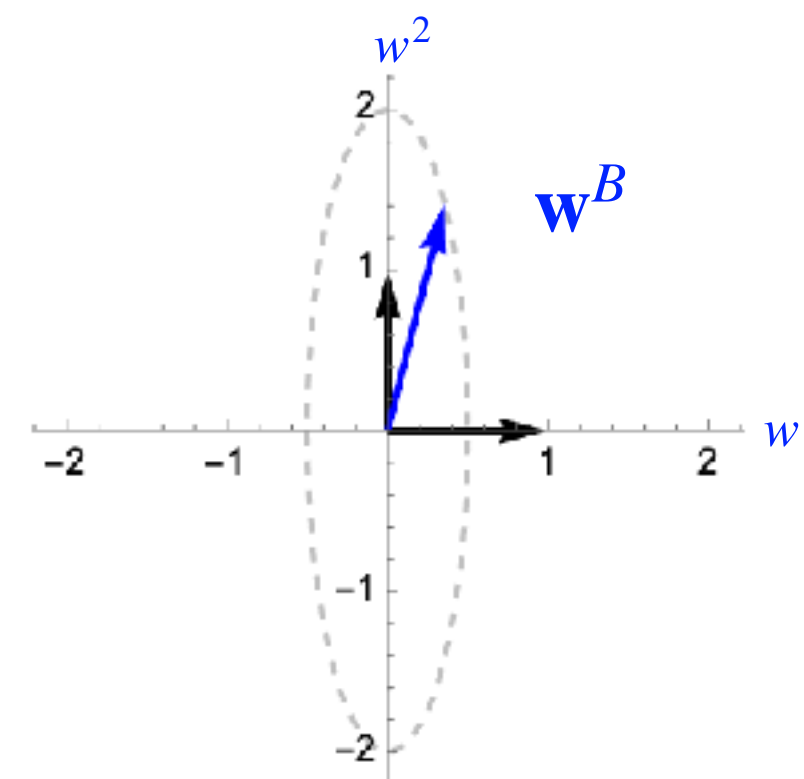


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Equivalence of group representations

A (matrix) representation is called **reducible** if it can be written as

$$\rho(g) = Q^{-1} (\rho_1(g) \oplus \rho_2(g)) Q = Q^{-1} \begin{pmatrix} \rho_1(g) & 0 \\ 0 & \rho_2(g) \end{pmatrix} Q$$

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Example: Steerable basis on S^1 (circular harmonics)

$Y(\alpha - \theta)$ $\rho(-\theta) = \bigoplus_{l=-L}^L \rho_l(-\theta)$ $Y(\alpha)$

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Real (irreducible) representations

$Y(\mathbf{R}_\theta^{-1} \mathbf{x}) = \rho(\mathbf{R}_\theta^{-1}) Y(\mathbf{x})$

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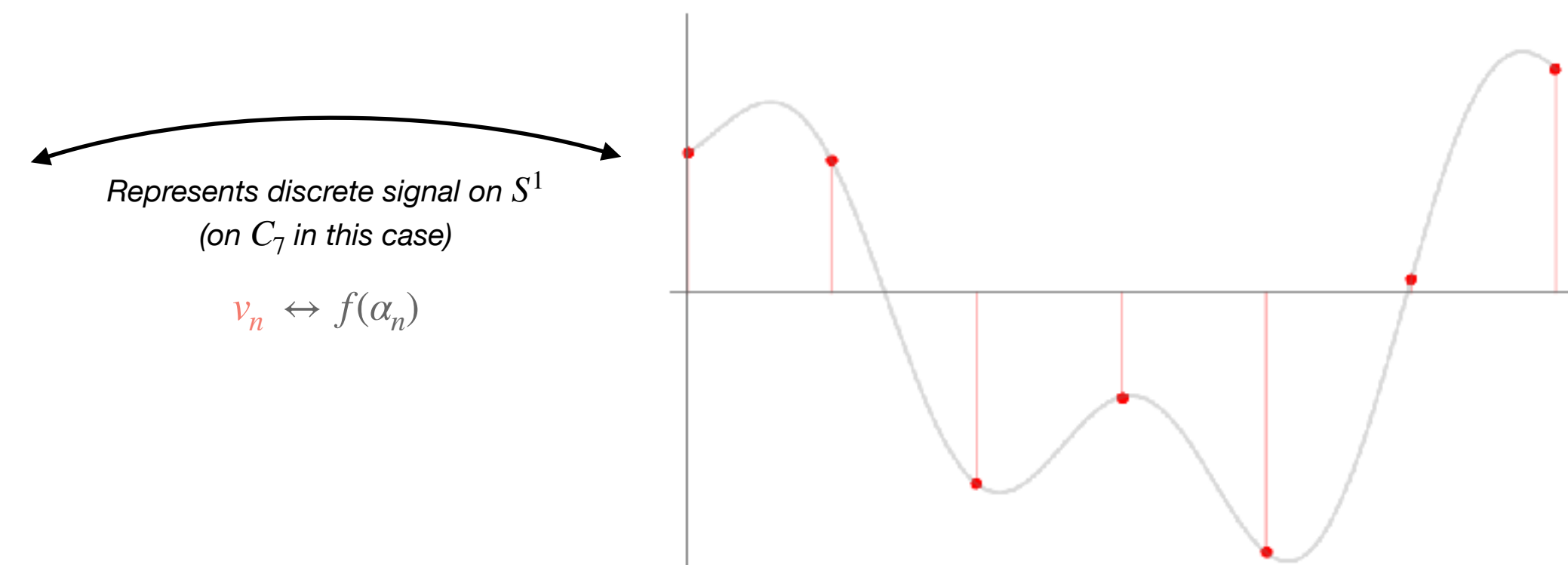
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$$\mathbf{v} \begin{pmatrix} 0.21 \\ 0.20 \\ -0.29 \\ -0.16 \\ -0.39 \\ 0.02 \\ 0.34 \end{pmatrix}$$



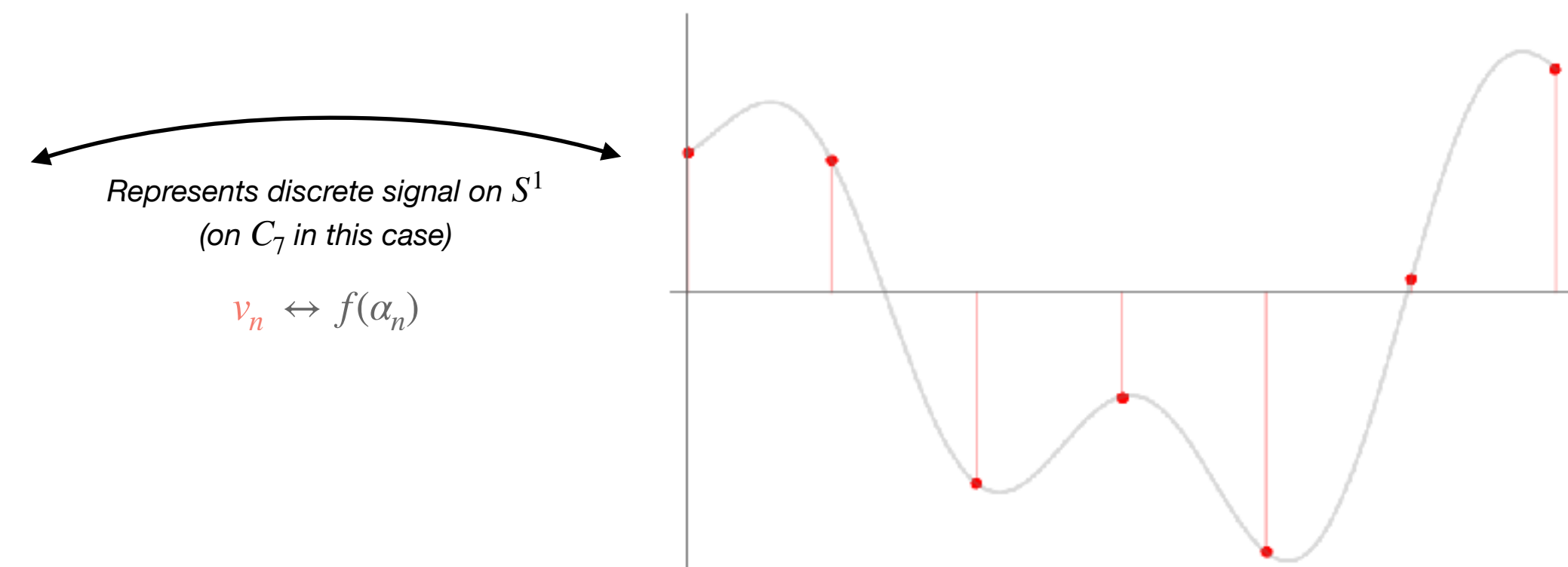
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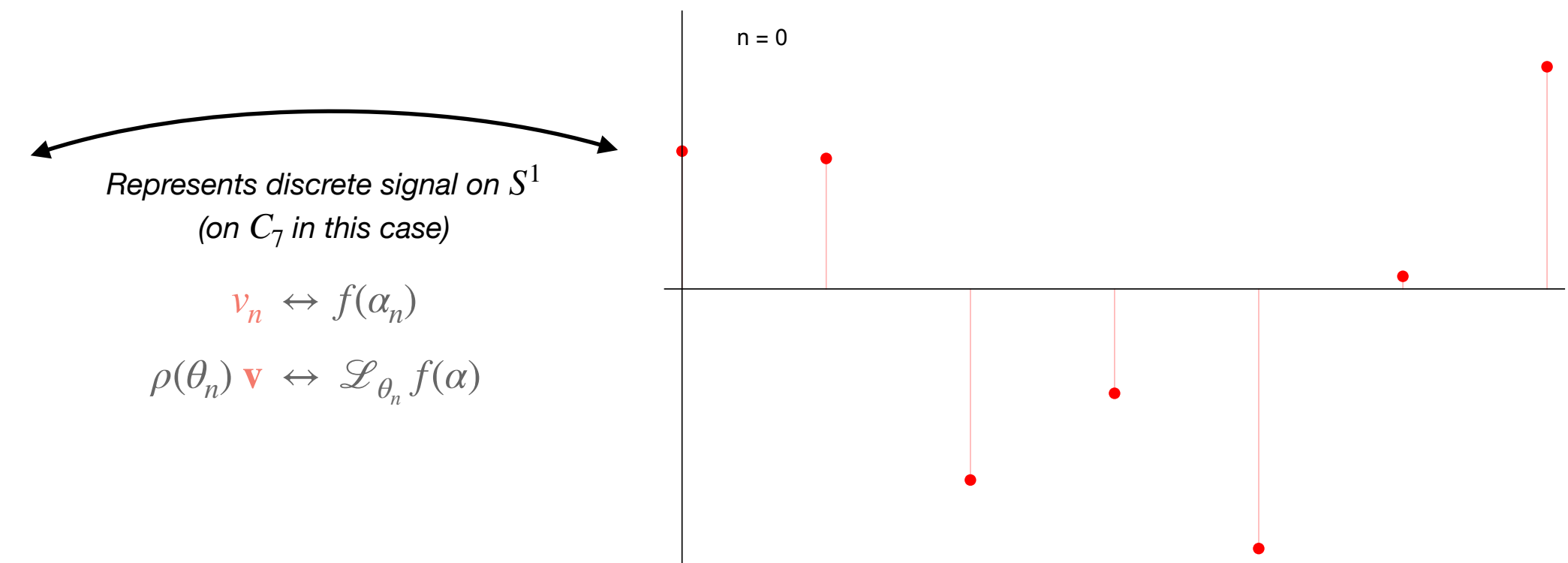
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$$\rho(\theta_n) \begin{pmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 \end{pmatrix}^n \begin{pmatrix} 0.21 \\ 0.20 \\ -0.29 \\ -0.16 \\ -0.39 \\ 0.02 \\ 0.34 \end{pmatrix}$$



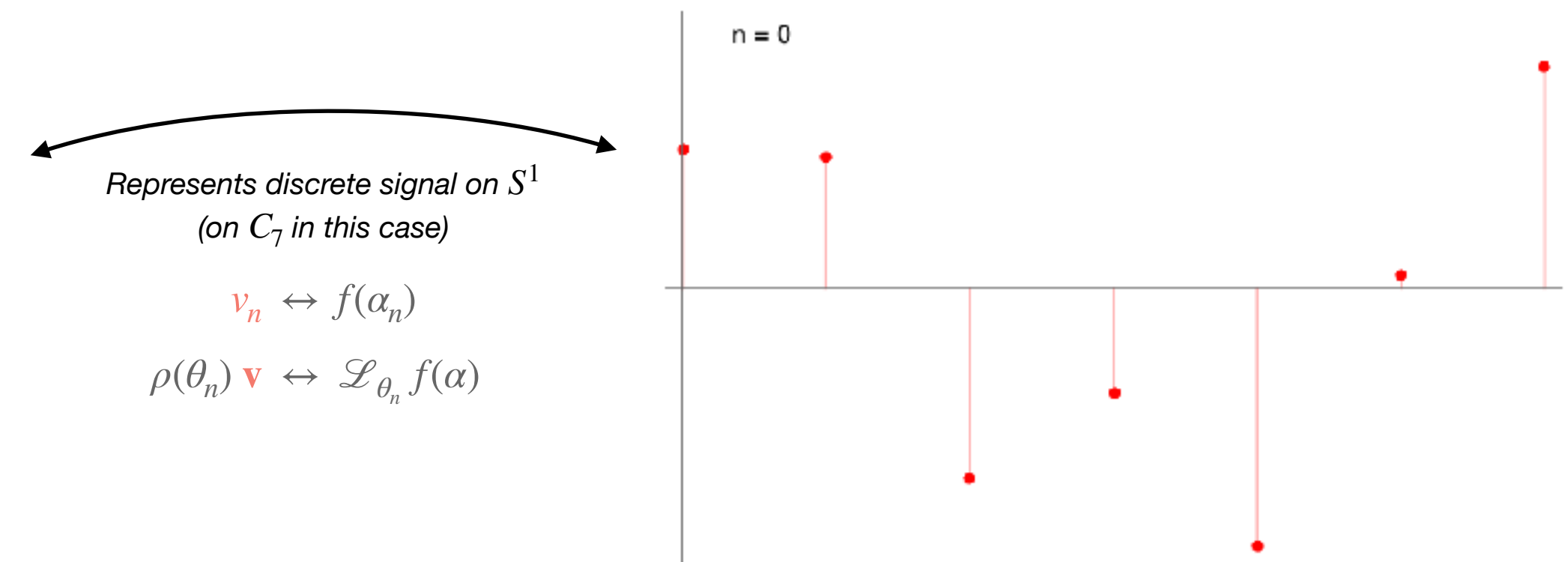
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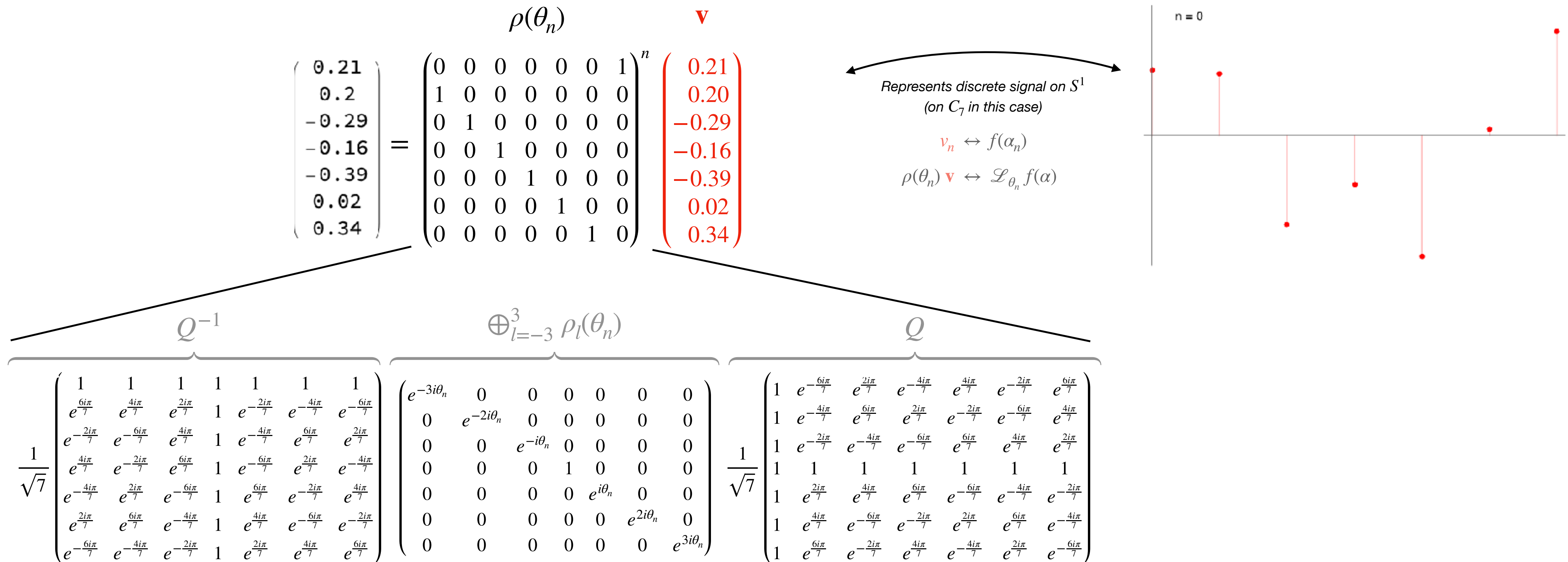


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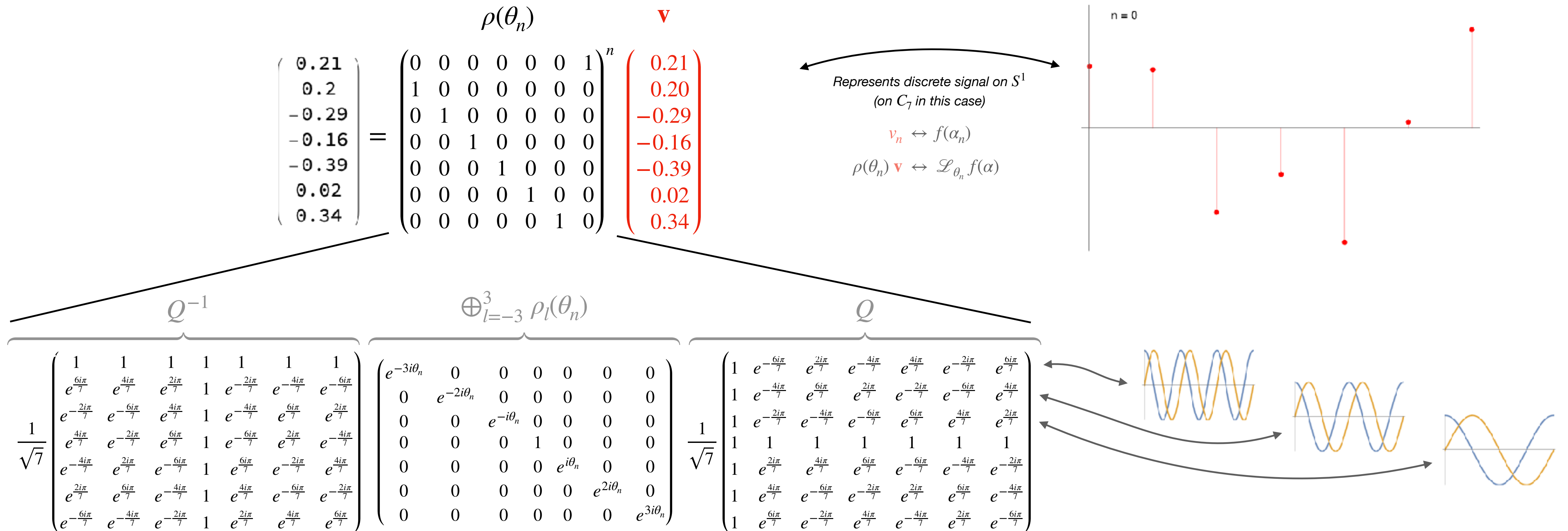


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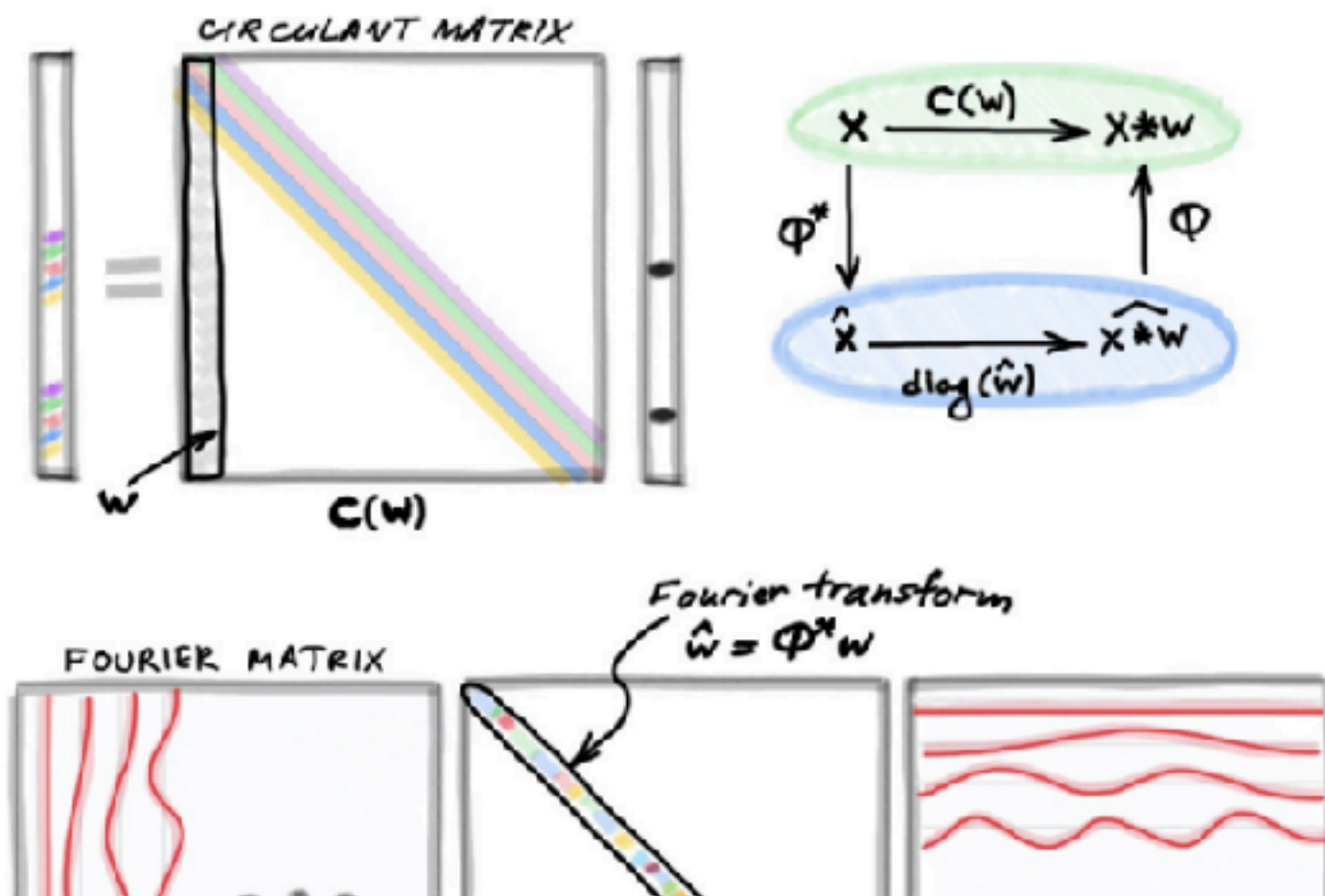
Derive Q (the irreps) yourself through an eigendecomposition of the circular shift matrix



BASICS OF DEEP LEARNING

Deriving convolution from first principles

Have you ever wondered what is so special about convolution? In this post, I derive the convolution from first principles and show that it naturally emerges from translational symmetry.



DISCOVERING TRANSFORMS: A TUTORIAL ON CIRCULANT MATRICES, CIRCULAR CONVOLUTION, AND THE DISCRETE FOURIER TRANSFORM

BASSAM BAMIEH*

4.1. Construction of Eigenvectors/Eigenvalues of S^* . Let w be an eigenvector (with eigenvalue λ) of the shift operator S^* . Note that it is also an eigenvector (with eigenvalue λ^l) of any power $(S^*)^l$ of S^* . Applying the definition (3.3) to the relation $S^*w = \lambda w$ will reveal that an eigenvector w has a very special structure

$$(4.1) \quad \begin{aligned} S^*w &= \lambda w & \iff & w_{k+1} = \lambda w_k, & k \in \mathbb{Z}_n, \\ (S^*)^l w &= \lambda^l w & \iff & w_{k+l} = \lambda^l w_k, & k \in \mathbb{Z}_n, l \in \mathbb{Z}, \end{aligned}$$

i.e. each entry w_{k+1} of w is equal to the previous entry w_k multiplied by the eigenvalue λ . These relations can be used to compute all eigenvectors/eigenvalues of S^* . First, observe that although (4.1) is valid for all $l \in \mathbb{Z}$, this relation “repeats” for $l \geq n$. In particular, for $l = n$ we have for each index k

$$(4.2) \quad w_{k+n} = \lambda^n w_k \iff w_k = \lambda^n w_k$$

since $k + n \equiv_n k$. Now since the vector $w \neq 0$, then for at least one index k , $w_k \neq 0$, and the last equality implies that $\lambda^n = 1$, i.e. any eigenvalue of S must be an n th root of unity

$$\lambda^n = 1 \iff \lambda = \rho_m := e^{i \frac{2\pi}{n} m}, \quad m \in \mathbb{Z}_n.$$

<https://towardsdatascience.com/deriving-convolution-from-first-principles-4ff124888028>

<https://arxiv.org/pdf/1805.05533.pdf>

Overview: Block-diagonalization via Fourier transform

Finite-dimensional vectors

$$\mathbf{v} \in \mathbb{R}^d$$

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$$f \in \mathbb{L}_2(G)$$

Regular representation

$$\rho(g_n) \mathbf{v}$$

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Decomposed into irreps

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$$Q \mathbf{v} = \frac{1}{\sqrt{7}} \begin{pmatrix} 1 & e^{-\frac{6i\pi}{7}} & e^{\frac{2i\pi}{7}} & e^{-\frac{4i\pi}{7}} & e^{\frac{4i\pi}{7}} & e^{-\frac{2i\pi}{7}} & e^{\frac{6i\pi}{7}} \\ 1 & e^{-\frac{4i\pi}{7}} & e^{\frac{6i\pi}{7}} & e^{\frac{2i\pi}{7}} & e^{-\frac{2i\pi}{7}} & e^{-\frac{6i\pi}{7}} & e^{\frac{4i\pi}{7}} \\ 1 & e^{-\frac{2i\pi}{7}} & e^{-\frac{4i\pi}{7}} & e^{-\frac{6i\pi}{7}} & e^{\frac{6i\pi}{7}} & e^{\frac{4i\pi}{7}} & e^{\frac{2i\pi}{7}} \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & e^{\frac{2i\pi}{7}} & e^{\frac{4i\pi}{7}} & e^{\frac{6i\pi}{7}} & e^{-\frac{6i\pi}{7}} & e^{-\frac{4i\pi}{7}} & e^{-\frac{2i\pi}{7}} \\ 1 & e^{\frac{4i\pi}{7}} & e^{-\frac{6i\pi}{7}} & e^{-\frac{2i\pi}{7}} & e^{\frac{2i\pi}{7}} & e^{\frac{6i\pi}{7}} & e^{-\frac{4i\pi}{7}} \\ 1 & e^{\frac{6i\pi}{7}} & e^{-\frac{2i\pi}{7}} & e^{\frac{4i\pi}{7}} & e^{-\frac{4i\pi}{7}} & e^{\frac{2i\pi}{7}} & e^{-\frac{6i\pi}{7}} \end{pmatrix} \begin{pmatrix} 0.21 \\ 0.20 \\ -0.29 \\ -0.16 \\ -0.39 \\ 0.02 \\ 0.34 \end{pmatrix}$$

$$[\mathcal{F}_G f]_l = \int_G \rho_l(g) f(g) dg$$

Inverse Fourier transform

$$Q^{-1} \hat{\mathbf{v}}$$

$$\mathcal{F}^{-1}[\hat{f}](g) = \sum_l \hat{f}(\rho_l) \rho_l(g^{-1})$$

General case $d_l \times d_l$ matrix irreps of compact groups

See e.g. Kondor, R., & Trivedi, S. (2018, July). On the generalization of equivariance and convolution in neural networks to the action of compact groups. In International Conference on Machine Learning (pp. 2747-2755). PMLR.

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Overview: Block-diagonalization via Fourier transform

Finite-dimensional vectors

$$\mathbf{v} \in \mathbb{R}^d$$

Infinite-dimensional vectors

$$f \in \mathbb{L}_2(G)$$

Regular representation

$$\rho(g_n) \mathbf{v}$$

$$\mathcal{L}_g f$$

Decomposed into irreps

$$Q^{-1} \left[\bigoplus_{l=-L}^L \rho_l(g_n) \right] Q$$

$$\mathcal{F}_G^{-1} \circ \left[\bigoplus_{l=-L}^L \rho_l(g) \right] \circ \mathcal{F}_G$$

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